

Gram - Schmidt Process

1. Orthogonal Bases:

A set $\{v_1, v_2, \dots, v_k\}$ of non-zero vectors in $\mathbb{R}^n$ is orthogonal if $v_i \cdot v_j = 0 \quad \forall i \neq j$.

Ex. 1 Find an ortho basis for the plane $2x - y + z = 0$ in $\mathbb{R}^3$.

Solution:

Let $y=0$ and $z=2$. x works out to be -1 .

$$v_1 = [-1, 0, 2]$$

Taking the coefficient of the plane, we get $[2, -1, 1]$.

$$\begin{aligned} v_2 &= [-1, 0, 2] \times [2, -1, 1] \\ &= [2, 5, 1] \end{aligned}$$

The ortho basis of the plane is $\{v_1, v_2\}$.

Note: Since we are finding an ortho basis for a plane in $\mathbb{R}^3$, we only need 2 vectors.

2. Projection Using an Ortho Basis:

Let $\{v_1, v_2, \dots, v_k\}$ be an ortho basis for a subspace W in $\mathbb{R}^n$. Let b be any vector in $\mathbb{R}^n$. The projection of b on W is:

$$bw = \frac{b \cdot v_1}{\|v_1\|^2} v_1 + \frac{b \cdot v_2}{\|v_2\|^2} v_2 + \dots + \frac{b \cdot v_k}{\|v_k\|^2} v_k$$

Fig. 2. Find the projection of $b = [3, -2, 2]$ on the plane $2x - y + z = 0$ in $\mathbb{R}^3$.

From 1, we found the ortho basis of the plane to be $\{[-1, 0, 2], [2, 5, 1]\}$.

$$\begin{aligned} bw &= \frac{b \cdot v_1}{\|v_1\|^2} v_1 + \frac{b \cdot v_2}{\|v_2\|^2} v_2 \\ &= \frac{[3, -2, 2] \cdot [-1, 0, 2]}{(-1)^2 + (2)^2} [-1, 0, 2] + \end{aligned}$$

$$\frac{[3, -2, 2] \cdot [2, 5, 1]}{(2)^2 + (5)^2 + (1)^2} [2, 5, 1]$$

$$= \frac{1}{5} [-1, 0, 2] - \frac{2}{30} [2, 5, 1]$$

$$= \left[-\frac{1}{3}, \frac{1}{3}, \frac{1}{3}\right]$$

3. Orthonormal Basis:

Let W be a subspace of $\mathbb{R}^n$. A basis $\{q_1, q_2, \dots, q_k\}$ for W is orthonormal if:

1. $q_i \cdot q_j = 0 \quad \forall i \neq j$

2. $q_i \cdot q_i = 1$

4. Projection of b on W with orthonormal basis:

$$bw = (b \cdot q_1)q_1 + (b \cdot q_2)q_2 + \dots$$

Note: $q_1 = \frac{v_1}{\|v_1\|^2}$, $q_2 = \frac{v_2}{\|v_2\|^2}$, $q_k = \frac{v_k}{\|v_k\|^2}$

E.g. 3. Find an orthonormal basis for $W = \text{sp}(v_1, v_2, v_3)$ in $\mathbb{R}^4$ if $v_1 = [1, 1, 1, 1]$, $v_2 = [-1, 1, -1, 1]$, $v_3 = [1, -1, -1, 1]$.

Then, find the projection of $b = [1, 2, 3, 4]$ on W .

Solution

$$v_1 \cdot v_2 = [1, 1, 1, 1] \cdot [-1, 1, -1, 1] = 0$$

$$v_1 \cdot v_3 = [1, 1, 1, 1] \cdot [1, -1, -1, 1] = 0$$

$$v_2 \cdot v_3 = [-1, 1, -1, 1] \cdot [1, -1, -1, 1] = 0$$

$$\text{Since } \|v_1\| = \|v_2\| = \|v_3\| = 2,$$

$$\text{Let } q_1 = \frac{1}{2}v_1, \quad q_2 = \frac{1}{2}v_2, \quad q_3 = \frac{1}{2}v_3.$$

$$\text{Then, } q_1 \cdot q_1 = 1, \quad q_2 \cdot q_2 = 1, \quad q_3 \cdot q_3 = 1.$$

$$q_1 = \left[\frac{1}{2}, \frac{1}{2}, \frac{1}{2}, \frac{1}{2} \right]$$

$$q_2 = \left[-\frac{1}{2}, \frac{1}{2}, -\frac{1}{2}, \frac{1}{2} \right]$$

$$q_3 = \left[\frac{1}{2}, -\frac{1}{2}, -\frac{1}{2}, \frac{1}{2} \right]$$

The orthonormal basis for W is $\{q_1, q_2, q_3\}$.

To find the projection of $b = [1, 2, 3, 4]$ on w , we do

$$\begin{aligned}bw &= (b \cdot q_1)q_1 + (b \cdot q_2)q_2 + (b \cdot q_3)q_3 \\&= ([1, 2, 3, 4] \cdot [\frac{1}{2}, \frac{1}{2}, \frac{1}{2}, \frac{1}{2}])([\frac{1}{2}, \frac{1}{2}, \frac{1}{2}, \frac{1}{2}]) + ([1, 2, 3, 4] \cdot [-\frac{1}{2}, \frac{1}{2}, -\frac{1}{2}, \frac{1}{2}]) \\&\quad ([-\frac{1}{2}, \frac{1}{2}, -\frac{1}{2}, \frac{1}{2}]) + ([1, 2, 3, 4] \cdot [\frac{1}{2}, -\frac{1}{2}, -\frac{1}{2}, \frac{1}{2}])([\frac{1}{2}, -\frac{1}{2}, -\frac{1}{2}, \frac{1}{2}]) \\&= [2, 3, 2, 3]\end{aligned}$$

5. Gram-Schmidt Thm:

Let $\{a_1, a_2, \dots, a_k\}$ be a basis of w .

We can use this thm to find an orthogonal basis of w . Let $\{v_1, v_2, \dots, v_k\}$ be an orthogonal basis for w .

$$v_1 = a_1$$

$$v_2 = a_2 - \left(\frac{a_2 \cdot v_1}{\|v_1\|^2} v_1 \right)$$

$$v_3 = a_3 - \left(\frac{a_3 \cdot v_1}{\|v_1\|^2} v_1 + \frac{a_3 \cdot v_2}{\|v_2\|^2} v_2 \right)$$

In general,

$$v_i = a_i - \left(\frac{a_i \cdot v_1}{\|v_1\|^2} v_1 + \frac{a_i \cdot v_2}{\|v_2\|^2} v_2 + \dots + \frac{a_i \cdot v_{i-1}}{\|v_{i-1}\|^2} v_{i-1} \right)$$

To find the orthonormal basis, let $q_i = \left(\frac{v_i}{\|v_i\|} \right)$

E.g. 4. Find an orthogonal and orthonormal for $W = \text{sp}([1,0,1], [1,1,1])$ of $\mathbb{R}^3$.

$$a_1 = [1,0,1] \rightarrow v_1 = a_1 = [1,0,1]$$

$$a_2 = [1,1,1]$$

$$v_2 = a_2 - \left(\frac{a_2 \cdot v_1}{\|v_1\|^2} v_1 \right)$$

$$= [1,1,1] - \frac{[1,1,1] \cdot [1,0,1]}{2} [1,0,1]$$

$$= [1,1,1] - [1,0,1]$$

$$= [0,1,0]$$

The orthogonal basis of W is $\{[1,0,1], [0,1,0]\}$.

To find the orthonormal basis:

$$q_1 = \frac{v_1}{\|v_1\|}$$

$$q_2 = \frac{v_2}{\|v_2\|}$$

$$= \frac{[1,0,1]}{\sqrt{1^2+0^2+1^2}}$$

$$= \frac{[0,1,0]}{\sqrt{0^2+1^2+0^2}}$$

$$= \frac{1}{\sqrt{2}} [1,0,1]$$

$$= [0,1,0]$$

An orthonormal basis is $\left\{ \left[\frac{1}{\sqrt{2}}, 0, \frac{1}{\sqrt{2}} \right], [0,1,0] \right\}$.

6. QR-Decomposition:

Let A be an $n \times k$ matrix with indep col vectors in $\mathbb{R}^n$. There exists an $n \times k$ matrix Q with orthonormal col vectors and an upper-triangular invertible $k \times k$ matrix R , s.t. $A = QR$.

E.g. 5.

$$\text{Let } A = \begin{bmatrix} 1 & 1 \\ 0 & 1 \\ 1 & 1 \end{bmatrix}$$

← These are the vectors taken from E.g. 4.

$$Q = \begin{bmatrix} \frac{1}{\sqrt{2}} & 0 \\ 0 & 1 \\ \frac{1}{\sqrt{2}} & 0 \end{bmatrix}$$

← Comes from the calculations done in E.g. 4.

$$QR = A$$

$$\begin{bmatrix} \frac{1}{\sqrt{2}} & 0 \\ 0 & 1 \\ \frac{1}{\sqrt{2}} & 0 \end{bmatrix} \begin{bmatrix} r_{11} & r_{12} \\ 0 & r_{22} \end{bmatrix} = \begin{bmatrix} 1 & 1 \\ 0 & 1 \\ 1 & 1 \end{bmatrix}$$

Find
 $R \rightarrow$

$$1. \begin{bmatrix} \frac{1}{\sqrt{2}}, 0 \end{bmatrix} \cdot \begin{bmatrix} r_{11}, 0 \end{bmatrix} = 1$$

$$\frac{r_{11}}{\sqrt{2}} = 1$$

$$r_{11} = \sqrt{2}$$

$$3. \begin{bmatrix} 0, 1 \end{bmatrix} \cdot \begin{bmatrix} r_{12}, r_{22} \end{bmatrix} = 1$$

$$r_{22} = 1$$

$$2. \begin{bmatrix} \frac{1}{\sqrt{2}}, 0 \end{bmatrix} \cdot \begin{bmatrix} r_{12}, r_{22} \end{bmatrix} = 1$$

$$\frac{r_{12}}{\sqrt{2}} = 1$$

$$r_{12} = \sqrt{2}$$

$$\begin{bmatrix} \frac{1}{\sqrt{2}} & 0 \\ 0 & 1 \\ \frac{1}{\sqrt{2}} & 0 \end{bmatrix} \begin{bmatrix} \sqrt{2} & \sqrt{2} \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 1 \\ 0 & 1 \\ 1 & 1 \end{bmatrix}$$

↑
 $QR = A$